Numerical Solutions to Stochastic Differential Equations

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- Stochastic Differential Equations
- Methods of Solution
- Example
- Orders of Approximation
- Future Work



Stochastic Process

What is it?

Coming from Probability Theory, a stochastic process is a collection of random variables that represent the evolution of a system over time.

You may of heard of:

- Markov Chains
- Queueing Theory
- Renewal Theory
- Brownian Motion

These are all stochastic processes!



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Andrey Markov



Stochastic Differential Equations

As we know, differential equations are useful tools in modeling real world behaviors like:

- An oscillating spring
- the trajectory of a object

Incorporate this idea with the random aspect of stochastic process, and we get a real world behavior that may have too many factors to predict in a deterministic fashion!

- Population growths with disease or natural disaster mechanics
- Queue lengths and expected wait times
- Game strategy (Stock market, betting, etc.)



Brownian Motion

A brief history,

- 1827- Initially discovered by a botanist, Robert Brown, when he noticed the movement of pollen in water to be very "random" and seemingly unexplainable
- 1905- Albert Einstein published a paper explaining Brown's observation with a mathematical model which helped solidify the theory of atoms and molecules
- 1908- Jean Perrin verified Einstein's model experimentally



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Brownian Motion

A Brownian Motion, B_t , can be approximated with a normal distribution if the time intervals are small enough.



The Euler-Maruyama Method

For first order Stochastic differential equations (SDEs), we can always reduce down to the form*:

$$dy = f(t, y)dt + g(t, y)dB_t$$

The Euler-Maruyama Method (Order $\frac{1}{2}$):

Denote $f_i = f(t_i, w_i)$ and $g_i = g(t_i, w_i)$,

 $w_0 = y_0$

$$w_{i+1} = w_i + f_i \Delta t_i + g_i \Delta B_i$$

(Recall $\Delta B_i \approx z_i \sqrt{\Delta t_i}$, this is where our order of $\frac{1}{2}$ comes from)



Other Methods

The Milstein Method (Order 1):

By taking Euler's out another term in the Taylor expansion,

$$w_0 = y_0$$

$$w_{i+1} = w_i + f_i \Delta t_i + g_i \Delta B_i + \frac{1}{2}g_i \cdot \frac{\partial g_i}{\partial y}((\Delta B_i)^2 - \Delta t_i)$$

First Order Runge-Kutta (Order 1):

Using a forward difference approximation on Milstein's,

$$w_0 = y_0$$

$$w_{i+1} = w_i + f_i \Delta t_i + g_i \Delta B_i \\ + \frac{1}{2\sqrt{\Delta t_i}} [g(t_i, w_i + g_i \sqrt{\Delta t_i}) - g_i]((\Delta B_i)^2 - \Delta t_i)$$



Example

A Geometric Brownian Motion	
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Consider
$$dy = \mu y dt + \sigma y dB$$

Solution:
$$y = y_0 e^{(\mu - \frac{1}{2}\sigma^2)t + \sigma B}$$

Choosing $\mu = .1$, $\sigma = .1$ and $y_0 = 1$, and using Euler's,



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Orders of Approximation

These standard methods of approximating SDEs have relatively low orders of approximation compared to ODEs. For example Eulers method is order 1 for ODEs but $\frac{1}{2}$ for SDEs.

A few reasons:

- No predictable patterns in Stochastic Process
- The error is a random variable
- Each realization will be different

An order of $\frac{1}{2}$ for a SDE approximation behaves quite well. Higher orders are possible at the cost of intense calculations.



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Notes

Itō's Lemma

If y = f(t, x), then

$$dy = \frac{\partial f}{\partial t}(t, x) dt + \frac{\partial f}{\partial x}(t, x) dx + \frac{1}{2} \frac{\partial^2 f}{\partial t^2}(t, x) dx dx$$

Where dt dt = 0, $dt dB_t = dB_t dt = 0$, and $dB_t dB_t = dt$

*-Using this lemma from Itō Calculus, we can reduce a SDE to

$$dy = f(t, y)dt + g(t, y)dB_t$$





- Re-write the Mathematica program!!!!
- Further research into probability measures and stochastic calculus
- Perhaps more work in relating numerical and stochastic process through the use of functional spaces.



Thank you!

Questions?



